

On Preemptive Scheduling on Uniform Machines to Minimize Mean Flow Time

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Abstract

In this paper we give a polynomial algorithm for problem $Q \mid r_j, p_j = p, \text{pmtn} \mid \sum C_j$ whose complexity status was open yet. The algorithm is based on a reduction of the scheduling problem to a linear program. The crucial condition for implementing the proposed reduction is the known order of job completion times.

Keywords: parallel uniform machines, linear programming, maximum flow, polynomial algorithm

1 Introduction

The problem considered can be stated as follows. There are n independent jobs and m parallel uniform machines. For each job J_j , $j = 1, \dots, n$, we know its processing time

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$p_j = p$ and its release time $r_j \geq 0$. Each machine M_q , $q = 1, \dots, m$, has some speed s_q , i.e. the execution of job J_j on machine M_q requires p/s_q time units. Any machine can process only one job at a time, and at any moment any job can be processed only by one but arbitrary machine. Preemptions of processing are allowed, i.e. the processing of any job may be interrupted at any time and resumed later, possibly on a different machine. We assume that all numerical data r_j, p, s_q are integers. For a schedule s , let $C_j(s)$ denote the time at which the processing of job J_j is completed. If no ambiguity arises, we drop the reference to schedule s and write C_j . The problem is to schedule all jobs so as to minimize the optimality criterion $\sum_{j=1}^n C_j$. The described problem can be denoted as $Q \mid r_j, p_j = p, \text{pmtn} \mid \sum C_j$.

Note that problem $P \mid r_j, \text{pmtn} \mid \sum C_j$ and, therefore, also problem $Q \mid r_j, \text{pmtn} \mid \sum C_j$ are unary NP-hard [1] whereas problem $Q \mid r_j, \text{pmtn} \mid C_{max}$ can be solved in $O(n \log n + mn)$ time [3]. Problem $R \mid r_j, \text{pmtn} \mid L_{max}$ can be effectively solved by reducing it to linear programming [5]. Problem $R \mid \text{pmtn} \mid \sum C_j$ is NP-hard in the strong sense, and problem $R \mid p_{ji} \in \{p_j, \infty\} \mid \sum C_j$ can be solved in $O(n^3)$ time [6].

The main result in this paper is a polynomial algorithm for problem $Q \mid r_j, p_j = p, \text{pmtn} \mid \sum C_j$. This result is a generalization of the polynomial algorithm for problem $P \mid r_j, p_j = p, \text{pmtn} \mid \sum C_j$ from paper [2]. Throughout the paper, we suppose that the jobs are enumerated in such a way that $r_1 \leq \dots \leq r_n$ holds. Furthermore, we assume that $r_1 = 0$.

2 A polynomial algorithm for problem $Q \mid r_j, p_j = p, \text{pmtn} \mid \sum C_j$

In this section, we derive a polynomial algorithm for problem $Q \mid r_j, p_j = p, \text{pmtn} \mid \sum C_j$.

Statement 1 *For problem $Q \mid r_j, p_j = p, \text{pmtn} \mid \sum C_j$ an optimal schedule can be found in the class of schedules, for which*

$$C_1 \leq \dots \leq C_n$$

holds.

Proof: Let $T_{kq}(t)$ be the total amount of time that machine M_q spends on job J_k in the time period $[0, t[$. Then, $f_k(t) = \sum_{q=1}^m T_{kq}(t) \cdot s_q$ is the part of job J_k processed in $[0, t[$. Suppose that in some optimal schedule, there are two jobs J_i and J_j such that $r_i < r_j$ and $C_i > C_j$ holds. Since $0 = f_j(r_j) \leq f_i(r_j)$ and $p = f_j(C_j) > f_i(C_j)$, there exists some time point $\xi \in [r_j, C_j]$ such that $f_j(\xi) = f_i(\xi)$, i.e. the part of job J_j processed in $[\xi, C_i[$ is equal to the part of job J_i processed in $[\xi, C_i[$. Now we can swap jobs J_i and J_j within the interval $[\xi, C_i[$. \square

In fact, for the proposed algorithm this simple statement plays a crucial role. In the following, we only deal with schedules from the described class. Let s^* be an optimal

schedule for problem $Q \mid r_j, p_j = p, \text{pmtn} \mid \sum C_j$ with $C_1(s^*) \leq \dots \leq C_n(s^*)$. Each $C_j(s^*)$ belongs to some interval $[r_i, r_{i+1}]$. However, if we know for each $C_j(s^*)$ the corresponding interval $[r_i, r_{i+1}]$ such that $C_j(s^*) \in [r_i, r_{i+1}]$, then an optimal schedule can be easily found using a reduction to a network flow problem. Thus, the main question is to know the interval $[r_i, r_{i+1}]$ for each $C_j(s^*)$ such that $C_j(s^*) \in [r_i, r_{i+1}]$. However, this difficulty can be avoided due to criterion $\sum C_j$. For any job J_j , let the time interval $[r_i, r_{i+1}]$ be such that $C_j \in [r_i, r_{i+1}]$. Taking into account that $r_1 = 0$, we obtain

$$C_j = (r_2 - r_1) + (r_3 - r_2) + \dots + (r_i - r_{i-1}) + (C_j - r_i).$$

Due to this property, we introduce the completion time of job J_j for each interval $[r_i, r_{i+1}]$. For each job J_j with $j = 1, \dots, n$ and for each interval $[r_i, r_{i+1}]$ with $i = 1, \dots, n$, we define the value $C(J_j, r_i)$ such that $C(J_j, r_i) = C_j(s^*)$ if $C_j(s^*) \in [r_i, r_{i+1}]$, but if $C_j(s^*) \leq r_i$, then we set $C(J_j, r_i) = r_i$, and if $C_j(s^*) \geq r_{i+1}$, then we set $C(J_j, r_i) = r_{i+1}$. Thus, for job J_j with $j = 1, \dots, n$, we have

$$C(J_j, r_i) = \begin{cases} C_j(s^*) & \text{if } r_i < C_j(s^*) < r_{i+1} \\ r_i & \text{if } C_j(s^*) \leq r_i \\ r_{i+1} & \text{if } C_j(s^*) \geq r_{i+1} \end{cases} \quad (2.1)$$

So, for each $i = 1, \dots, n$, the values

$$r_i \leq C(J_1, r_i) \leq \dots \leq C(J_i, r_i) \leq C(J_{i+1}, r_i) = \dots = C(J_n, r_i) = r_{i+1}$$

define a partition of the interval $[r_i, r_{i+1}]$. Here, we set $r_{n+1} = r_n + n \cdot \max_q \{p/s_q\}$, i.e. r_{n+1} is a time point after which no job will be processed.

In turn, each interval $[C(J_j, r_i), C(J_{j+1}, r_i)]$ is completely defined by the jobs processed in it. Thus, we denote by $v(J_k, M_q, J_j, r_i)$ the part of job J_k processed in the interval $[C(J_{j-1}, r_i), C(J_j, r_i)]$ by machine M_q , i.e. the total processing time of job J_k in the interval $[C(J_{j-1}, r_i), C(J_j, r_i)]$ equals $\frac{v(J_k, M_q, J_j, r_i)}{s_k}$ and for any job J_k , equality

$$\sum_{q=1}^m \sum_{i=1}^n \sum_{j=1}^n v(J_k, M_q, J_j, r_i) = p$$

holds.

The values $C(J_j, r_i)$, where $j = 1, \dots, n$, $i = 1, \dots, n$, and the values $v(J_k, M_q, J_j, r_i)$, where $i, j = 1, \dots, n$, $k = j, \dots, i$, $q = 1, \dots, m$, define a feasible solution of the following linear program. For convenience, we introduce $C(J_0, r_i) = r_i$.

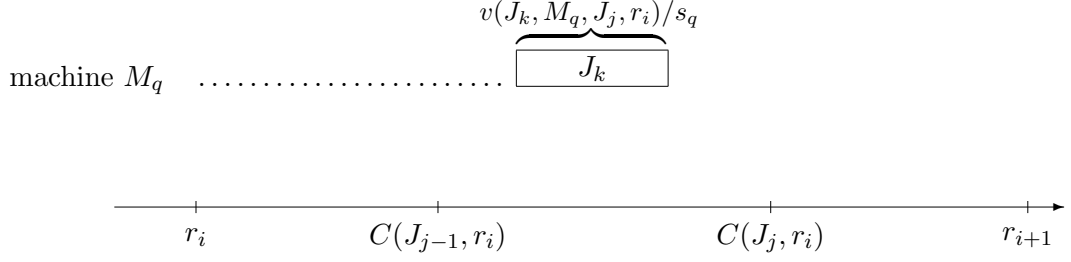


Figure 1: Here $v(J_k, M_q, J_j, r_i)$ is the part of job J_k processed within $[C(J_{j-1}, r_i), C(J_j, r_i)]$.

Minimize

$$\sum_{i=1}^n \left((C(J_1, r_i) - r_i) + \dots + (C(J_n, r_i) - r_i) \right) \quad (2.2)$$

subject to

$$\begin{aligned} r_i = C(J_0, r_i) \leq C(J_1, r_i) \leq \dots \leq C(J_{i+1}, r_i) = \dots \\ = C(J_n, r_i) = r_{i+1}, \quad i = 1, \dots, n \end{aligned} \quad (2.3)$$

$$\begin{aligned} \sum_{q=1}^m \frac{v(J_k, M_q, J_j, r_i)}{s_q} \leq C(J_j, r_i) - C(J_{j-1}, r_i), \\ i = 1, \dots, n, \quad j = 1, \dots, n, \quad k = 1, \dots, n \end{aligned} \quad (2.4)$$

$$\begin{aligned} \sum_{k=1}^n \frac{v(J_k, M_q, J_j, r_i)}{s_q} \leq C(J_j, r_i) - C(J_{j-1}, r_i), \\ i = 1, \dots, n, \quad j = 1, \dots, n, \quad q = 1, \dots, m \end{aligned} \quad (2.5)$$

$$\sum_{i=1}^n \sum_{j=1}^n \sum_{q=1}^m v(J_k, M_q, J_j, r_i) = p, \quad k = 1, \dots, n \quad (2.6)$$

$$\begin{aligned} v(J_k, M_q, J_j, r_i) = 0 \quad i = 1, \dots, n-1, \quad j = i+1, \dots, n, \\ q = 1, \dots, m, \quad k = 1, \dots, n \end{aligned} \quad (2.7)$$

$$\begin{aligned} v(J_k, M_q, J_j, r_i) = 0 \quad i = 1, \dots, n, \quad j = 1, \dots, i, \\ q = 1, \dots, m, \quad k = 1, \dots, j-1 \end{aligned} \quad (2.8)$$

$$\begin{aligned} v(J_k, M_q, J_j, r_i) = 0 \quad i = 1, \dots, n-1, \quad j = 1, \dots, i, \\ q = 1, \dots, m, \quad k = i+1, \dots, n \end{aligned} \quad (2.9)$$

$$C(J_j, r_i) \geq 0 \quad i = 1, \dots, n, \quad j = 1, \dots, n \quad (2.10)$$

$$v(J_k, M_q, J_j, r_i) \geq 0 \quad \begin{array}{l} i = 1, \dots, n, \quad j = 1, \dots, n, \\ k = 1, \dots, n, \quad q = 1, \dots, m. \end{array} \quad (2.11)$$

The above formulation includes $O(mn^3)$ variables and constraints, i.e. this problem can be polynomially solved.

Note that:

- Constraints (2.3) hold since in $[r_i, r_{i+1}[$ only jobs J_1, \dots, J_i can be processed. Jobs J_{i+1}, \dots, J_n are available only after r_{i+1} .
- Constraints (2.4) hold since $\sum_{q=1}^m \frac{v(J_k, M_q, J_j, r_i)}{s_q}$ is the total time of processing job J_k in the time interval $[C(J_{j-1}, r_i), C(J_j, r_i)[$, see Figure 1.
- Inequalities (2.5) are true since $\sum_{k=1}^n \frac{v(J_k, M_q, J_j, r_i)}{s_q}$ is the total time when machine M_q is busy in $[C(J_{j-1}, r_i), C(J_j, r_i)[$. Note that constraints (2.4) and (2.5) provide the possibility to schedule all parts $v(J_k, M_q, J_j, r_i)$ within the time interval $[C(J_{j-1}, r_i), C(J_j, r_i)]$ in a feasible way.
- Constraints (2.6) hold since $\sum_{i=1}^n \sum_{j=1}^n \sum_{q=1}^m v(J_k, M_q, J_j, r_i)$ is the total part of job J_k being processed.
- Constraints (2.7) hold since

$$C(J_{i+1}, r_i) = C(J_{i+2}, r_i) = \dots = C(J_n, r_i) = r_{i+1},$$

i.e. there are no jobs processed in $[C(J_{i+1}, r_i), r_{i+1}[$.

- Constraints (2.8) hold since jobs J_1, \dots, J_{j-1} cannot be processed after time point $C(J_{j-1}, r_i)$, see Figure 1.
- Constraints (2.9) hold since jobs J_{i+1}, \dots, J_n cannot be processed before time point r_{i+1} , see Figure 1.
- Furthermore, for schedule s^* function (2.2) corresponds to the optimality criterion $\sum_{j=1}^n C_j$, since

$$C(J_j, r_i) - r_i = \begin{cases} C_j(s^*) - r_i & \text{if } r_i < C_j(s^*) < r_{i+1} \\ 0 & \text{if } C_j(s^*) \leq r_i \\ r_{i+1} - r_i & \text{if } C_j(s^*) \geq r_{i+1} \end{cases}$$

and therefore, $\sum_{i=1}^n (C(J_j, r_i) - r_i) = C_j(s^*)$.

Thus, $\sum_{i=1}^n \left((C(J_1, r_i) - r_i) + \dots + (C(J_n, r_i) - r_i) \right) = \sum_{j=1}^n C_j(s^*)$.

Summarizing, we have proven

Theorem 1 *For any optimal schedule s^* of problem $Q \mid r_j, p_j = p, pmtn \mid \sum C_j$, there is a corresponding feasible solution of (2.2)-(2.11) such that $C_1(s^*) \leq \dots \leq C_n(s^*)$ and*

$$\sum_{j=1}^n C_j(s^*) = \sum_{i=1}^n \left((C(J_1, r_i) - r_i) + \dots + (C(J_n, r_i) - r_i) \right)$$

hold.

The next theorem shows that conversely any feasible solution of (2.2)-(2.11) also provides a feasible schedule.

Theorem 2 *Any feasible solution of problem (2.2)-(2.11) provides a feasible schedule s^* for the scheduling problem $Q \mid r_j, p_j = p, pmtn \mid \sum C_j$ such that*

$$\sum_{j=1}^n C_j(s^*) = \sum_{i=1}^n \left((C(J_1, r_i) - r_i) + \dots + (C(J_n, r_i) - r_i) \right)$$

holds.

Proof: Any feasible solution of (2.2)-(2.11) provides some values $C(J_j, r_i)$ and $v(J_k, M_q, J_j, r_i)$, and hence it provides some feasible schedule, which can be reconstructed by processing all parts $v(J_k, M_q, J_j, r_i)$ in the intervals $[C(J_{j-1}, r_i), C(J_j, r_i)[$. If the values $C(J_j, r_i)$ obtained are such that for any job J_j , there is an index e such that $C(J_j, r_i) = r_{i+1}$ holds for any $r_i < r_e$ and $C(J_j, r_i) = r_i$ holds for any $r_i > r_e$, then for the schedule s^* defined by $C(J_j, r_i)$ and $v(J_k, M_q, J_j, r_i)$ equality

$$\sum_{j=1}^n C_j(s^*) = \sum_{i=1}^n \left((C(J_1, r_i) - r_i) + \dots + (C(J_n, r_i) - r_i) \right)$$

holds. Thus, in this case Theorem 2 is true.

Now suppose that for some job J_j , there does not exist such an index e . In this case, one can find two intervals $[r_k, r_{k+1}[$ and $[r_h, r_{h+1}[$ such that $r_k \leq C(J_j, r_k) < r_{k+1} \leq r_h < C(J_j, r_h) \leq r_{h+1}$ holds. Transform the schedule s^* in the following way. Take the largest value of δ such that in $[C(J_j, r_k), C(J_j, r_k) + \delta]$ and in $[C(J_j, r_h), C(J_j, r_h) - \delta]$, each machine is either idle or processes exactly one job. Now we swap J_j from the interval $[C(J_j, r_h), C(J_j, r_h) - \delta]$ and J_l (if any) from the interval $[C(J_j, r_k), C(J_j, r_k) + \delta]$ on the same machine, say M_z (see Figure 2). Since in $[r_k, r_{k+1}[$ inequality $C(J_l, r_k) > C(J_j, r_k)$ holds, it follows that inequality $r_j \leq r_l$ holds. This implies $C(J_l, r_h) \geq C(J_j, r_h)$ and $\sum C_j$ does not change.

Now, if it happens that J_l is processed in $[C(J_j, r_h), C(J_j, r_h) - \delta]$ by some other machine, say $M_g \neq M_z$, then we swap job J_l from $[C(J_j, r_h), C(J_j, r_h) - \delta]$ and J_f (if any) from

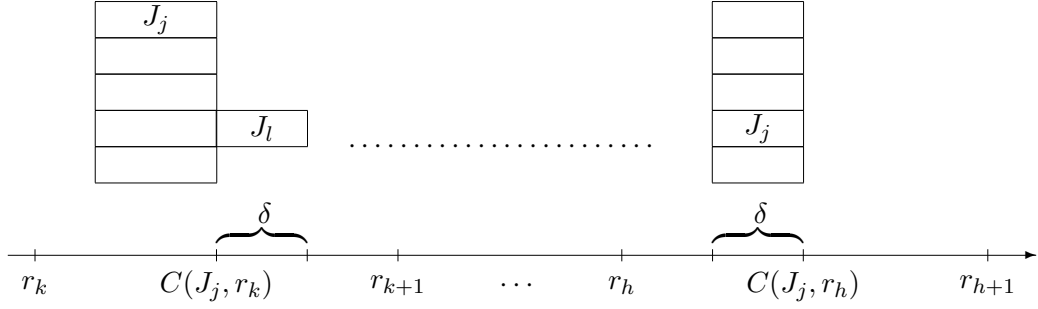


Figure 2: Swap of J_j from $[C(J_j, r_h), C(J_j, r_h) - \delta]$ and J_l from $[C(J_j, r_k), C(J_j, r_k) + \delta]$.

$[C(J_j, r_k), C(J_j, r_k) + \delta]$ on machine M_g . We will continue with this swapping as long as the schedule remains infeasible. Note that the value of (2.2) does not increase. \square

Example. Let us consider the instance from [2]. The data are the following: $m = 3$, $p = 10$, $r_1 = \dots = r_5 = 0$, $r_6 = r_7 = 11$, $r_8 = r_9 = 18$, $r_{10} = 22$, $r_{11} = 27$. Let the speeds be $s_1 = 1$, $s_2 = 1$, and $s_3 = 2$. Using CPLEX ², we solve the corresponding LP problem. We obtain an optimal solution with the objective function value 196.54296875 and with the following non-zero variables:

$C(J_0, r_6) = 11,$	$C(J_0, r_7) = 11,$	$C(J_0, r_8) = 18,$	$C(J_0, r_9) = 18,$
$C(J_0, r_{10}) = 22,$	$C(J_0, r_{11}) = 27,$	$C(J_0, r_6) = 11,$	$C(J_0, r_7) = 11,$
$C(J_0, r_8) = 18,$	$C(J_0, r_9) = 18,$	$C(J_0, r_{10}) = 22,$	$C(J_0, r_{11}) = 27,$
$C(J_1, r_5) = 5,$	$C(J_1, r_6) = 11,$	$C(J_1, r_7) = 11,$	$C(J_1, r_8) = 18,$
$C(J_1, r_9) = 18,$	$C(J_1, r_{10}) = 22,$	$C(J_1, r_{11}) = 27,$	$C(J_2, r_5) = 7.5,$
$C(J_2, r_6) = 11,$	$C(J_2, r_7) = 11,$	$C(J_2, r_8) = 18,$	$C(J_2, r_9) = 18,$
$C(J_2, r_{10}) = 22,$	$C(J_2, r_{11}) = 27,$	$C(J_3, r_5) = 10.5,$	$C(J_3, r_6) = 11,$
$C(J_3, r_7) = 11,$	$C(J_3, r_8) = 18,$	$C(J_3, r_9) = 18,$	$C(J_3, r_{10}) = 22,$
$C(J_3, r_{11}) = 27,$	$C(J_4, r_5) = 11,$	$C(J_4, r_6) = 11,$	$C(J_4, r_7) = 11,$
$C(J_4, r_8) = 18,$	$C(J_4, r_9) = 18,$	$C(J_4, r_{10}) = 22,$	$C(J_4, r_{11}) = 27,$
$C(J_5, r_5) = 11,$	$C(J_5, r_6) = 11,$	$C(J_5, r_7) = 14.25,$	$C(J_5, r_8) = 18,$
$C(J_5, r_9) = 18,$	$C(J_5, r_{10}) = 22,$	$C(J_5, r_{11}) = 27,$	$C(J_6, r_5) = 11,$
$C(J_6, r_6) = 11,$	$C(J_6, r_7) = 17.625,$	$C(J_6, r_8) = 18,$	$C(J_6, r_9) = 18,$
$C(J_6, r_{10}) = 22,$	$C(J_6, r_{11}) = 27,$	$C(J_7, r_5) = 11,$	$C(J_7, r_6) = 11,$
$C(J_7, r_7) = 18,$	$C(J_7, r_8) = 18,$	$C(J_7, r_9) = 19.3125,$	$C(J_7, r_{10}) = 22,$
$C(J_7, r_{11}) = 27,$	$C(J_8, r_5) = 11,$	$C(J_8, r_6) = 11,$	$C(J_8, r_7) = 18,$
$C(J_8, r_8) = 18,$	$C(J_8, r_9) = 22,$	$C(J_8, r_{10}) = 23.65625,$	$C(J_8, r_{11}) = 27,$
$C(J_9, r_5) = 11,$	$C(J_9, r_6) = 11,$	$C(J_9, r_7) = 18,$	$C(J_9, r_8) = 18,$
$C(J_9, r_9) = 22,$	$C(J_9, r_{10}) = 23.9140625,$	$C(J_9, r_{11}) = 28.9140625,$	$C(J_{10}, r_5) = 11,$
$C(J_{10}, r_6) = 11,$	$C(J_{10}, r_7) = 18,$	$C(J_{10}, r_8) = 18,$	$C(J_{10}, r_9) = 22,$
$C(J_{10}, r_{10}) = 27,$	$C(J_{10}, r_{11}) = 28.9140625,$	$C(J_{11}, r_5) = 11,$	$C(J_{11}, r_6) = 11,$
$C(J_{11}, r_7) = 18,$	$C(J_{11}, r_8) = 18,$	$C(J_{11}, r_9) = 22,$	$C(J_{11}, r_{10}) = 27,$
$C(J_{11}, r_{11}) = 32.95703125,$			

²CPLEX is a trademark of ILOG, Inc. <http://www.ilog.com/products/cplex/>

$$\begin{aligned}
v(J_1, M_3, J_1, r_5) &= 10, & v(J_2, M_1, J_1, r_5) &= 3.5, & v(J_2, M_2, J_1, r_5) &= 1.5, \\
v(J_3, M_1, J_1, r_5) &= 1.5, & v(J_4, M_2, J_1, r_5) &= 3.5, & v(J_2, M_3, J_2, r_5) &= 5, \\
v(J_3, M_1, J_2, r_5) &= 2.5, & v(J_4, M_2, J_2, r_5) &= 2.5, & v(J_3, M_3, J_3, r_5) &= 6, \\
v(J_4, M_1, J_3, r_5) &= 3, & v(J_5, M_2, J_3, r_5) &= 3, & v(J_4, M_3, J_4, r_5) &= 1, \\
v(J_5, M_1, J_4, r_5) &= 0.5, & v(J_5, M_3, J_5, r_7) &= 6.5, & v(J_6, M_2, J_5, r_7) &= 3.25, \\
v(J_7, M_1, J_5, r_7) &= 3.25, & v(J_6, M_3, J_6, r_7) &= 6.75, & v(J_7, M_1, J_6, r_7) &= 3.375, \\
v(J_7, M_3, J_7, r_7) &= 0.75, & v(J_7, M_3, J_7, r_9) &= 2.625, & v(J_8, M_2, J_7, r_9) &= 1.3125, \\
v(J_9, M_1, J_7, r_9) &= 1.3125, & v(J_8, M_3, J_8, r_9) &= 5.375, & v(J_9, M_2, J_8, r_9) &= 2.6875, \\
v(J_8, M_3, J_8, r_{10}) &= 3.3125, & v(J_9, M_1, J_8, r_{10}) &= 1.65625, & v(J_{10}, M_2, J_8, r_{10}) &= 1.65625, \\
v(J_9, M_3, J_9, r_{10}) &= 0.515625, & v(J_{10}, M_1, J_9, r_{10}) &= 0.2578125, & v(J_{10}, M_3, J_{10}, r_{10}) &= 6.171875, \\
v(J_9, M_3, J_9, r_{11}) &= 3.828125, & v(J_{10}, M_1, J_9, r_{11}) &= 1.9140625, & v(J_{11}, M_2, J_9, r_{11}) &= 1.9140625, \\
v(J_{11}, M_3, J_{11}, r_{11}) &= 8.0859375.
\end{aligned}$$

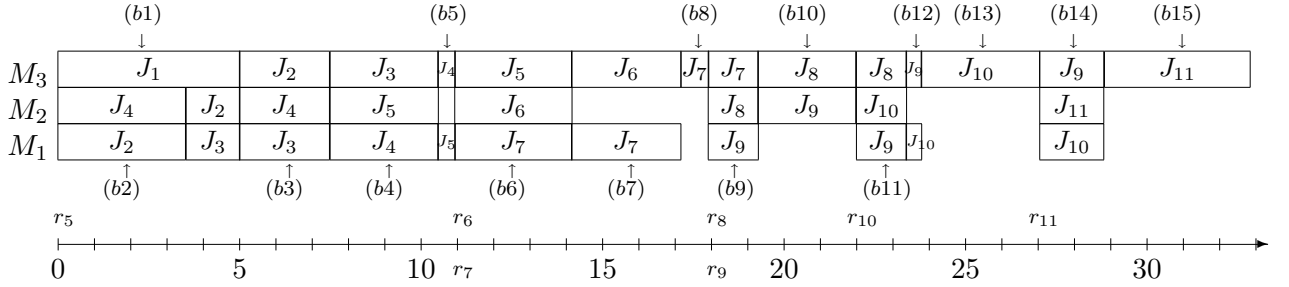


Figure 3: The optimal schedule corresponding to the CPLEX solution. Here (b1) corresponds to $v(J_1, M_3, J_1, r_5) = 10$, (b2) corresponds to $v(J_2, M_1, J_1, r_5) = 3.5$, (b3) corresponds to $v(J_3, M_1, J_2, r_5) = 2.5$, (b4) corresponds to $v(J_4, M_1, J_3, r_5) = 3$, (b5) corresponds to $v(J_4, M_3, J_4, r_5) = 1$, (b6) corresponds to $v(J_7, M_1, J_5, r_7) = 3.25$, (b7) corresponds to $v(J_7, M_1, J_6, r_7) = 3.375$, (b8) corresponds to $v(J_7, M_3, J_7, r_7) = 0.75$, (b9) corresponds to $v(J_9, M_1, J_7, r_9) = 1.3125$, (b10) corresponds to $v(J_8, M_3, J_8, r_9) = 5.375$, (b11) corresponds to $v(J_9, M_1, J_8, r_{10}) = 1.65625$, (b12) corresponds to $v(J_9, M_3, J_9, r_{10}) = 0.515625$, (b13) corresponds to $v(J_{10}, M_3, J_{10}, r_{10}) = 6.171875$, (b14) corresponds to $v(J_9, M_3, J_9, r_{11}) = 3.828125$, (b15) corresponds to $v(J_{11}, M_3, J_{11}, r_{11}) = 8.0859375$.

The solution is defined by the five non-zero intervals $[r_5, r_6[= [0, 11[$, $[r_7, r_8[= [11, 18[$, $[r_9, r_{10}[= [18, 22[$, $[r_{10}, r_{11}[= [22, 27[$, and $[r_{11}, r_{12}[= [27, 137[$. For $[r_5, r_6[$, we get $C(J_1, r_5) = 5$, $C(J_2, r_5) = 7.5$, $C(J_3, r_5) = 10.5$, $C(J_4, r_5) = 11$. For $[r_7, r_8[= [11, 18[$, we get $C(J_4, r_7) = 11$, $C(J_5, r_7) = 14.25$, $C(J_6, r_7) = 17.625$, $C(J_7, r_7) = 18$. For $[r_9, r_{10}[= [18, 22[$, we have $C(J_6, r_9) = 18$, $C(J_7, r_9) = 19.3125$, $C(J_8, r_9) = 22$, $C(J_9, r_9) = 22$. For $[r_{10}, r_{11}[= [22, 27[$, we have $C(J_7, r_{10}) = 22$, $C(J_8, r_{10}) = 23.65625$, $C(J_9, r_{10}) = 23.9140625$, $C(J_{10}, r_{10}) = 27$. For $[r_{11}, r_{12}[= [27, 137[$, we have $C(J_8, r_{11}) = 27$, $C(J_9, r_{11}) = 28.9140625$, $C(J_{10}, r_{11}) = 28.9140625$, $C(J_{11}, r_{11}) = 32.95703125$.

In Figure 4, we leave only blocks corresponding to such values $v(J_k, M_q, J_j, r_i)$ that define the C_j values for each interval $[r_i, r_{i+1}[$.

From Figure 4, one can see that (2.1) holds for each job except job J_9 , since $r_{10} < C(J_9, r_{10}) < r_{11}$ and $r_{11} < C(J_9, r_{11}) < r_{12}$. Therefore, for all jobs except job J_9 , we have $C_1 = C(J_1, r_5) = 5$, $C_2 = C(J_2, r_5) = 7.5$, $C_3 = C(J_3, r_5) = 10.5$, $C_4 = C(J_4, r_5) = 11$, $C_5 = C(J_5, r_7) = 14.25$, $C_6 = C(J_6, r_7) = 17.625$, $C_7 = C(J_7, r_9) = 19.3125$, $C_8 =$

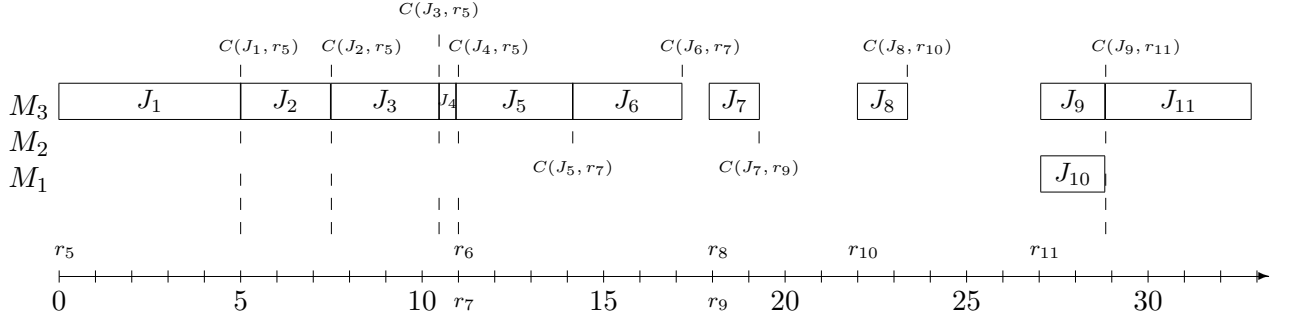


Figure 4: Here each block corresponds to such a value $v(J_k, M_q, J_j, r_i)$ that defines $C(J_j, r_i)$.

$C(J_8, r_{10}) = 23.65625$, $C_{10} = C(J_{10}, r_{11}) = 28.9140625$, $C_{11} = C(J_{11}, r_{11}) = 32.95703125$. For job J_9 , see Figure 3, we have $C_9 = C(J_9, r_{11}) = 28.9140625$, but from (2.2) we calculate the value

$$\begin{aligned}
C_9 &= \sum_{i=1}^{11} (C(J_9, r_i) - r_i) \\
&= (C(J_9, r_1) - r_1) + (C(J_9, r_2) - r_2) + (C(J_9, r_3) - r_3) + (C(J_9, r_4) - r_4) + \\
&\quad (C(J_9, r_5) - r_5) + (C(J_9, r_6) - r_6) + (C(J_9, r_7) - r_7) + (C(J_9, r_8) - r_8) + \\
&\quad (C(J_9, r_9) - r_9) + (C(J_9, r_{10}) - r_{10}) + (C(J_9, r_{11}) - r_{11}) \\
&= (0 - 0) + (0 - 0) + (0 - 0) + (0 - 0) + (11 - 0) + (11 - 11) + (18 - 11) + \\
&\quad (18 - 18) + (22 - 18) + (23.9140625 - 22) + (28.9140625 - 27) \\
&= 25.828125.
\end{aligned}$$

To get the schedule with $C_9 = 25.828125$, one can apply the transformation described in the proof of Theorem 2. In the first step, we swap a part of job J_9 with length δ and a part of job J_{10} with length δ on machine M_3 , see Figure 5. After the first step, we

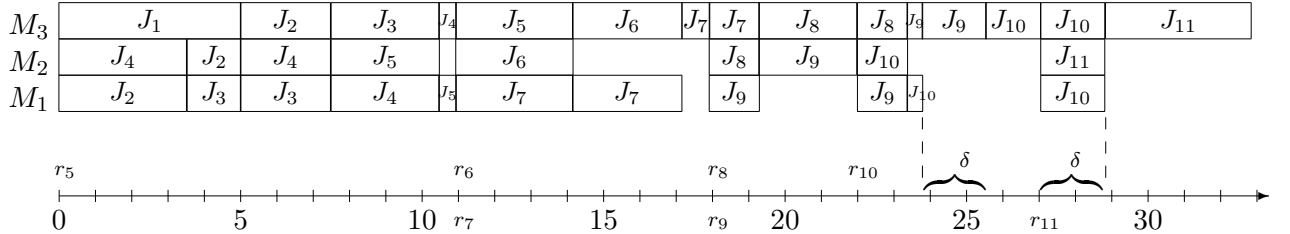


Figure 5: The schedule obtained after the first step of the transformation.

obtain an infeasible schedule, see Figure 5, since job J_{10} is processed on machine M_3 and machine M_1 at the same time. Nevertheless, the value of (2.2) is not changed. In the

next step of the transformation, we swap a part of job J_{10} with length δ with the idle interval of length δ on machine M_1 , see Figure 6. The obtained schedule is feasible and the value of (2.2) is not changed, but now we have

$$C_9 = C(J_9, r_{10}) + \frac{1}{2} \cdot v(J_9, M_3, J_9, r_{11}) = 23.9140625 + \frac{1}{2} \cdot 3.828125 = 25.828125$$

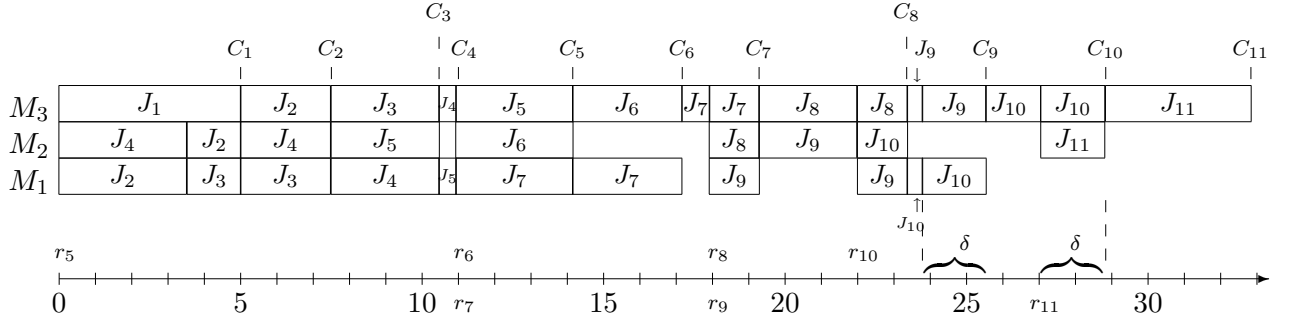


Figure 6: The schedule obtained after the second step of the transformation.

Thus, one can see that we do not need to apply the transformation. Since as a result of solving (2.2)-(2.11) we obtain the values C_1, \dots, C_n , we can reconstruct the optimal schedule by solving the following network flow problem, see [4].

Suppose that all points $r_1, \dots, r_n, C_1, \dots, C_n$ are enumerated in non-decreasing order of their values, say $t_1 \leq \dots \leq t_k$. We construct a network which has the following vertices:

- a source u and a sink w ,
- job-vertices $\{J_j \mid j = 1, \dots, n\}$,
- machine-time-interval-vertices $\{(t_i, t_{i+1}, M_e) \mid i = 1, \dots, k - 1, \quad e = 1, \dots, m\}$

The arcs in the network defined are the following:

- for each job-vertex J_j , there is an arc (u, J_j) with the capacity p , and there is an arc $(J_j, (t_i, t_{i+1}, M_e))$ if $r_j \leq t_i$ and $t_{i+1} \leq C_j$ hold,
- for each vertex (t_i, t_{i+1}, M_e) , there is an arc $((t_i, t_{i+1}, M_e), w)$ with the capacity $(t_{i+1} - t_i) \cdot s_e$.

Any maximal flow will reconstruct an optimal schedule.

Thus, to solve problem $Q \mid r_j, p_j = p, \text{pmtn} \mid \sum C_j$, one has to do the following:

1. Solve the corresponding linear program (2.2)-(2.11), and calculate the values $C_j = \sum_{i=1}^n (C(J_j, r_i) - r_i)$ for each job J_j .
2. Reconstruct an optimal schedule by solving the corresponding network flow problem.

3 Concluding remarks

In this paper, we considered problem $Q \mid r_j, p_j = p, \text{pmtn} \mid \sum C_j$, whose complexity status was open yet. We presented a polynomial algorithm which is based on the solution of a linear program and a network flow problem. For further research, the most interesting question is whether it is possible to simplify the proposed linear programming formulation in the same way as it was made in [1] for problem $P \mid r_j, p_j = p, \text{pmtn} \mid \sum C_j$. In particular, is it possible to find such special properties of an optimal schedule which permit to reduce the size of the linear programming formulation?

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